Farshad Samadi Kohnehshahri

Ph.D. Student & Researcher Fellow in Bioengineering University of Bologna



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Education

Ph.D. Student in Bioengineering

University of Bologna, Italy

Nov 2022 - Present

Research Topic:

Identification of Patterns and Biomarkers in the Gait of Patients with Neurological Pathologies using Classical Techniques and Machine Learning

Supervisor: Prof. Rita Stagni Co-Supervisor: Dr. Andrea Merlo

M.Sc. In Electrical Engineering (Control)

University of Tabriz, Iran

Sep 2010 - Jan 2013

Research Topic:

Real-Time Ankle Adjustment and Gait Generation of

Humanoid Robot in Rough Terrains

Supervisor: Prof. S. Khanmohammadi

Co-Advisor: Prof. A. R. Ghiasi

B.Sc. in Electronic Engineering

Urmia University, Iran

Sep 2005- Sep 2009

Research Topic:

PID control of AC motor using PLC and Inverter

Supervisor: Prof. D. Nazarpour

Research Interests

- Rehabilitation
- Gait and Motion Analysis
- Machine Learning Algorithms
- Pattern Generation for Humanoid Robots
- Human-Robot Interacting Systems

Teaching Assistantship

University of Tabriz

Jan 2012- Jan 2013- Tabriz, Iran

Achievements/Tasks

Linear Control Systems

Teacher: Dr. A. R Ghiasi

Robotics

Teacher: Dr. A. R Ghiasi

Engineering Math Teacher: Dr. M. Badamchizadeh

Linear Control Systems Teacher: Dr. S. Ghaemi

Work Experiences

Milad In Hospital

08/2016 - 11/2022, Urmia, Iran International Medical Center

Achievements/Tasks

- Involving in Al and Robotic systems
- Rehabilitation systems
- Research on application of AI methods in medical procedures
- Preventive Maintenance for mechatronics, and Medical Systems
- Development of maintenance policies and guidelines
- Root Cause Analysis for system failures
- · Troubleshooting of mechatronics and electrical systems
- · Planning periodic tests and evaluation of systems
- Identification of critical failures for systems and proposing preventive methods
- Documentation and analysis of the outcome of the applied maintenance system
- Designing electrical and mechatronic systems
- Design and Integration of control systems for ensuring high reliability and safety

Pakdis Co.

02/2016-08/2016, Urmia, Iran

one of the leading companies in providing different kinds of fruit juice and beverages in Iran

Achievements/Tasks

- Maintenance of electrical and instrumentation systems
- Design and Integration of sensors and actuators with control systems in product lines
- Troubleshooting of mechatronics and electrical systems
- Programming and troubleshooting of PLCs
- Root Cause Analysis for failures
- Investigation of the integration of control schemes in mechatronic systems
- Developing precision systems to perform reliability and safety in the product lines

Fazar Tajhiz Jam Co.

03/2015-02/2016. Tehran, Iran

one of the main suppliers of measurement equipment in the petrochemical industry such as Gas Analyzers, Gas & Liquid Flowmeters

Achievements/Tasks

- Design and Implementation of gas analyzing systems including control and Instrumentation integration
- Test and calibration of sensory measuring equipment
- Documentation and extracting As-Built plans for projects

Asan Pak Sanat Co.

05/2014 - 03/2015, Tehran, Iran

Food Sector of Tomra Company in Iran and supplier of Sorter Machines

Achievements/Tasks

- Installing and customer service for sorter machines
- Installing, Implementation, and Troubleshooting of X-RAY sorters
- Involving in laser sorter machines and troubleshooting of mechatronic parts, laser generators, optics, and software
- Implementation and Troubleshooting of colored sorters

Certificates

Programmable Logic Controllers

09/2012

Professional Technical Organization/ Iran

Embedded C Programming

06/2014

Tehran Institute of Technology/ Iran

ARM 7

08/2014

Tehran Institute of Technology/ Iran

Language Skills

• English Fluent (Overall Score in IELTS: 6.5)

Turkish Fluent

Azeri *Mother tongue*Persian *Mother tongue*

Hobbies

- Studying
- Sport (Basketball, Volleyball, Workout)
- Watching Movie
- Walking

Publications

 Farshad Samadi, Sohrab khanmohammadi, Amir R.Ghiasi, "Foot and Body Control of Humanoid Robots using Fuzzy Algorithm", International Journal of Robotics and Automation. Vol 32, Issue 4,2017.

- Saeed Aghaie, Sohrab Khanmohammadi, Hamid Moghadamfar and Farshad Samadi, "Adaptive Vision Based Control of Robot Manipulators Using the Interpolating Polynomial", Transactions of the Institute of Measurement and Control. vol. 36 no.6, pp 837-844, August 2014.
- Hamid Mogadamfar, Sohrab Khanmohammadi, Sahraneh Gaemi, Farshad Samadi, "Human Age-Group Estimation Based on ANFIS using the HOG and IBP features", Electrical and Electronic Engineering: An International Journal EEEIJ, Vol 2, No 1, February 2013.
- Hamid Moghadam-Fard and Farshad Samadi, "Active Suspension System Control Using Adaptive Neuro Fuzzy (ANFIS) Controller", IJE TRANSACTIONS C: Aspects Vol. 28, No. 3 (March 2015) 360-369
- Farshad Samadi, Hamid Moghadamfard, "Pattern Generation for Humanoid Robot with Natural ZMP Trajectories", IEEE 2nd RSI International conference on Robotics and Mechatronics, 15-17 October 2014, Tehran, Iran.
- Sohrab Khanmohammadi, Amir R. Ghiasi, Farshad Samadi "Real-time pattern generation for humanoid robot to walk on rough terrain using preview control", 9th International Conference on Electronics, Computer and Computation, 1st- 3st nov 2012 Ankara, Turkey.
- Aliasghar Keyvani, Morteza Sadeghi, Farshad Samadi, "Computation of Electromagnetic Field Distribution on a MEMS Proximeter Using Meshless Galerkin Method", 1st National conference on MEMS 16-17 Nov. 2011 Khoy Azad university, Iran.